

	Test Report	
	EN ISO 13849-1:2015	
	BS EN 62061:2015	
Responsibility		
Tested by (printed name and signature)	Charles Li	Charles Li Jeny-zheng
Approved by (printed name and signature)	Jerry Zheng	Jeny zheng
Date of issue	2019-12-06	
Testing Laboratory Name	SGS-CSTC Standards Techr	nical Services (Shanghai) Co., Ltd.
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Manufacturer's Name	Same as applicant.	
Address	Same as applicant.	
Test specification		
Standard	EN ISO 13849-1:2015 & BS E	EN 62061: 2015
Test procedure	SGS-CSTC	
Non-standard test method	N/A	
Test Report Form No.	BMS HFT=0_A	
TRF originator	SGS-CSTC	
Master TRF	Dated	
Products may only be provided with an a © Publication in total or in part and/or re allowed unless permission has been exp	production in whatever way of	the contents of this report is not
Test Item Description	BMS for EPAC battery packa	lge
Trademark	N/A	
Model and/or type reference	Refer to page 4	
HW Version	KL96UF04A	
Rating(s)		

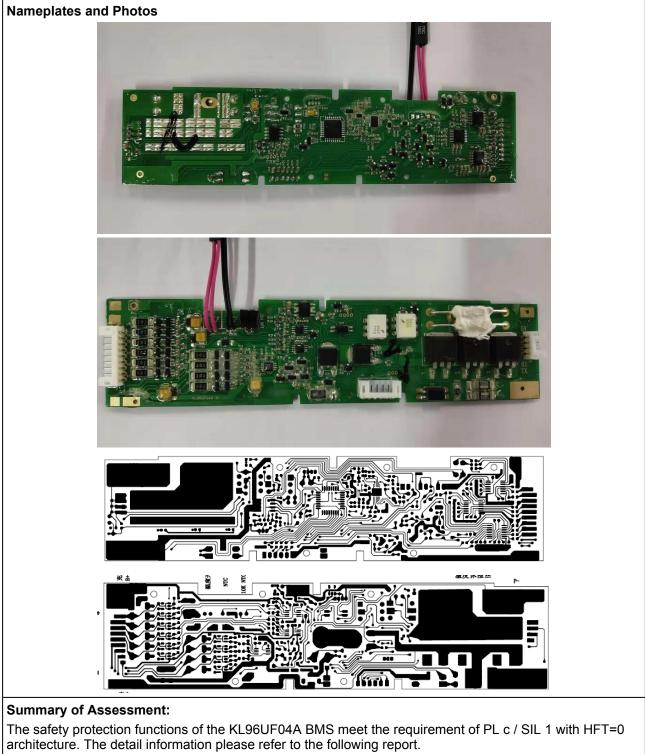


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Over C	harge Protection	4.30±0.025V
2nd-lev	vel over Charge Protection:	4.45±0.025V
Under	Discharge Protection	2.50±0.025V
Over-c	urrent Protection	40A±5A
Short-c	circuit Protection	OUT+/OUT- Short Current
Over-T	emp Protection for Charge:	>70°C: Can not Charge & Discharge
		<0°C or >50℃: Can not Charge
Test C	ase Verdicts	
Test ca	ase does not check to the test c	object N/C
Test ca	ase does not apply to the test o	bject N/A
	em does meet the requirement	
Test ite	em does not meet the requirem	ient F(ail)
Testin	g	
Date of	f receipt of test item	
Date(s	) of performance of test	2019-11-09 to 2019-11-12
The tes " (see r "(see A		opended to the report.
Refere		
No.	Document Description	
[1]	KL96UF04A _PCB Layout_v	1.0
[2]	KL96UF04A_FMEDA_BMS_v	v1.0
[3]	KL96UF04A_Structure Block	_v1.0
Revisi	on Logs	
Versio	on Changes Description	
v1.0	Initial Version	







#### Models of battery pack listed below are evaluated with BMS board version KL96UF04A.

#### A3 A6 A7 A8 A1 A2 A4 A5 A1: Type of battery pack A7: Lithium battery cells type and manufactures, it may be as below Code Description Model Cell Code Manufactory KL E-bike battery pack UR18650AA 082 Panasonic A2: Special function/design to this E-bike battery pack, it may be as below 902 NCR18650ZM Panasonic 089/809 NCR18650PF Panasonic Code Description 804 NCR18650B Panasonic С Customized the case design 909 NCR18650BD Panasonic U USB 906 NCR18650GA Panasonic D Handle Bar 70G Panasonic NCR2170G 0 Special charging Port 803 ICR18650-22P Samsung A3: rate voltage, it may be as below 806 ICR18650-26J Samsung Code Description 30Q INR18650-30Q Samsung 21/22/23/24/25 24V INR18650-29E 819 Samsung 34/35/36/37/38/39 36V 916 INR18650-35E Samsung 42 42V 50E INR21700-50E Samsung 47/48/49 48V M26 LG INR18650M26 other 2 digital number Customer code like 99/96/77 M29 INR18650M29 LG A4: BMS function, it may be as below LG INR18650MH1 908 Code Description 907 INR18650MJ1 LG P/PS/PH/PV with sleep mode function M50 INR21700M50 LG TP/TPH/TPV with sleep mode function 080 INR18650D205 YikLik/YLE H/HS/S without sleep mode function 083 INR18650A220 YikLik/YLE HU/HL/UL/UF/UY UART communication protocol 82V INR18650D220 YikLik/YLE CF/CB CANBus communication protocol Yikl ik/Yl F 826 INR18650D260 A5. Serial No., it may be 00-99 or 001-999 INR18650D290 YikLik/YLE 89D Code Description 300 INR18650A300 YikLik/YLE 2 digital number xx 340 INR18650A340 YikLik/YLE ххх 3 digital number A8: BMS Version, it may be as below A6: Colour for battery cases, it may be as below Description Code Code Description KL96UF04A E version В Black S Sliver Y Yellow А White υ Blue RW Bright white Example: KLC96UF04B.809E KL: E-bike battery pack C: Customized 96: Customer code & Rated voltage 36.0V UF: UART communication protocol

#### Name rule of battery packs specified by manufacture as below:

TRF No. BMS HFT=0 A

04: serial number B: Black case

E: BMS of E version

809: Cell type NCR18650PF, manufactory: Panasonic



#### 1. Safety Function

Prevention of risk of fire in case of management system failure for batteries, following protection circuits have been defined as safety related function in BMS Part:

- Over/under voltage protection
- Over current (short) protection
- Over/under temperature protection

The behaviors of the safety function under fault condition were defined as switching off charging or discharging MOSFET within the specified response time. **Note:** 

The protection function of the BMS circuit included primary protection circuit, without secondary protection circuit, so the architecture of protection function could be considered as HFT =0 per BS EN 62061:2015.

# Information on the recommended application of IEC 62061 and this part of ISO 13849

IEC 62061 and this part of ISO 13849 specify requirements for the design and implementation of safety-related control systems of machinery. The use of either of these International Standards, in accordance with their scopes, can be presumed to fulfil the relevant essential safety requirements. ISO/TR 23849 gives guidance on the application of this part of ISO 13849 and IEC 62061 in the design of safety-related control systems for machinery. BS EN 62061 was referred to executed performance level assessment in this report.

#### 2. Risk Assessment

Per the Figure A.1 of ISO 13849-1:2015

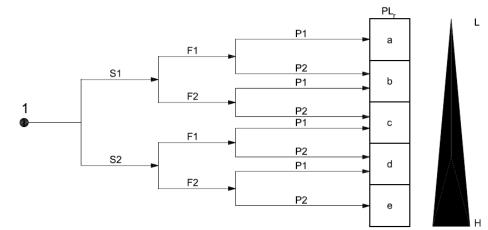


Figure 1 Risk Assessment

The required performance level as the following table.

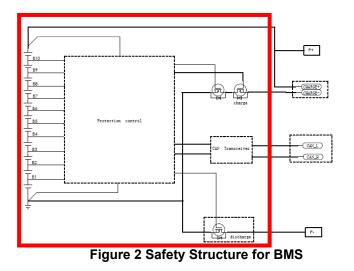
Paramete	er	Result	Rationale	Required PLr
S	Severity of injury	S1	Only slight injuries	С



F2	Frequency of exposure	Frequency of exposureF2Frequently or continuously expo
Frequently or continuo		usly expo

**Note:** According to EN 15194:2017 Clause 4.3.22 (a type C standard), the Performance Level of Prevention of risk of fire in case of management system failure for batteries with capacity above 100Wh shall be PLr c.

# 3. Safety Block Diagram



#### Note:

Cells voltage acquisition module, Current acquisition module, temperature acquisition module, Protect IC, charging and discharging MOS circuit composed of safety related circuit in this BMS project.

#### Structure Analysis:

Category and circuit modules description as below table:

Category Modules	Circuit modules description
Input	Cells voltage acquisition module, Current acquisition module, temperature acquisition module
Logic	Protect IC
Output	charging and discharging MOS

#### **Result:**

According to above analysis and safety structure diagram, the protection function of the BMS circuit included primary protection circuit, without secondary protection circuit, so the architecture of protection function could be considered as HFT =0 per BS EN 62061:2015.

#### 4. Calculate the MTTFd / PFH

Analysis:



The system MTTFd / PFH has been calculated based on schematic and BoM, the calculation report has been checked and confirmed, the total system MTTFd is 298.4 years, PFH is 3.83 \* 10<sup>-7</sup>.

Table 3 of BS EN 62061:2015 is used as the guideline to estimate the target failure values of the system, which in fact is noted as PFH<sub>D</sub>.

Safety integrity level	Probability of a dangerous Failure per Hour ( <i>PFH</i> <sub>D</sub> )
3	>= 10 <sup>-8</sup> to < 10 <sup>-7</sup>
2	>= 10 <sup>-7</sup> to < 10 <sup>-6</sup>
1	>= 10 <sup>-6</sup> to < 10 <sup>-5</sup>

#### **Result:**

Per table 3 of BS EN 62061:2015., the calculated value for the system  $PFH_D = 3.83 \times 10^{-7}$  results in a **SIL 2** level of target failure values.

#### 5. Calculate the Safe Failure Fraction (SFF)

According to "KL96UF04A\_FMEDA\_BMS\_v1.0", SFF for this system is 67.42% (>= 60%).

#### 6. Quantify SIL/PL Based On Input Parameters

The BMS protection circuit has been designed with the architecture of HFT = 0, SFF = 67.42% was evaluated. According to table 5 – architectural constraints on subsystems: maximum SIL that can be claimed for a SRCF using this subsystem, SIL1 could be claimed for this BMS protection circuit.

Safe Failure	Hardware Fault Tolerance		
Fraction	0	1	2
60% - < 90%	SIL1	SIL2	SIL3
90% - < 99%	SIL2	SIL3	SIL3
≥ 99%	SIL3	SIL3	SIL3

### Result:

Above table is used to determine the SIL of the system, the system design (SFF and HFT) results in SIL 1.

#### 7. Conclusions and Recommendations

The safety functions of the KL96UF04A BMS has been assessed to achieve SIL1 with HFT=0, according to the table 3 of EN ISO 13849-1:2015, it could be used in **PL c** application.

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# 8. Systematic Failure

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### 8.1 Introduction

When electrical systems are used in conjunction with other technologies, then relevant tables for basic safety and well-tried safety principles should also be taken into account.

# 8.2 List of basic safety principles

Table D.1 — Basic safety principles	

Clause	Requirement + Test	Result - Remark	Verdict
	Use of suitable materials and adequate manufacturing Selection of material, manufacturing methods and treatment in relation to e. g. stress, durability, elasticity, friction, wear, corrosion, temperature, conductivity, dielectric rigidity.	Refer to the BMS BOM.	Р
	Correct dimensioning and shaping Consider e. g. stress, strain, fatigue, surface roughness, tolerances, manufacturing.	Not assessed in project	N/C
	Proper selection, combination, arrangements, assembly and installation of components/system Apply manufacturer's application notes, e. g. catalogue sheets, installation instructions, specifications, and use of good engineering practice.	Work products in main phase are available. The battery user manual is available.	Ρ
	Correct protective bonding One side of the control circuit, one terminal of the operating coil of each electromagnetic operated device or one terminal of other electrical device is connected to the protective bonding circuit [for full text see EN 60204-1:1997 (IEC 60204-1:1997), 9.1.4].	No such case	N/A
	Insulation monitoring Use of isolation monitoring device which either indicates an earth fault or interrupts the circuit automatically after an earth fault [see EN 60204- 1:1997 (IEC 60204-1:1997), 9.4.3.1].	No such case	N/A
	Use of de-energisation principle A safe state is obtained by de-energising all relevant devices, e. g. by using of normally closed (NC) contact for inputs (push- buttons and position switches) and normally open (NO) contact for relays [see also EN 292–2:1991 (ISO/TR 12100-2:1992), 3.7.1]. Exceptions may exist in some applications, e. g. where the loss of the electrical supply will create an additional hazard. Time delay functions may be necessary to achieve a system safe state [see EN 60204–1:1997 (IEC 60204-1:1997), 9.2.2].	Not this situation	N/A
	Transient suppression Use of a suppression device (RC, diode, varistor) parallel to the load, but not parallel to the contacts.	The general transient suppression was designed in BMS board according to the schematic.	Р
	Reduction of response time Minimise delay in de–energising of switching components.	Manufacture has taken measures to minimise response time	Ρ
	Compatibility Use components compatible with the voltages and currents used.	All components meet the requirements of volt and current rated value.	Р

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Clause	Requirement + Test	Result - Remark	Verdict
	Withstanding environmental conditions Design the equipment so that it is capable of working in all expected environments and in any foreseeable adverse conditions, e. g. temperature, humidity, vibration and electromagnetic interference (EMI)	The product has been executed EMC testing according to EN115194 requirement, all testing items passed, EMC testing report is available.	Ρ
	Secure fixing of input devices Secure input devices, e. g. interlocking switches, position switches, limit switches, proximity switches, so that position, alignment and switching tolerance is maintained under all expected conditions, e. g. vibration, normal wear, ingress of foreign bodies, temperature. See EN 1088:1995 (ISO 14119:1998), clause 5.	No such case	N/A
	Protection against unexpected start–up Prevent unexpected start–up, e. g. after power supply restoration [see EN 292–2:1991 (ISO/TR 12100-2:1992), 3.7.2, EN 1037 (ISO 14118), EN 60204–1 (IEC 60204-1)].	No such case, this BMS always monitoring battery in its life cycling	N/A
	Protection of the control circuit The control circuit should be protected in accordance with EN 60204- 1:1997 (IEC 60204:-1:1997), 7.2 and 9.1.1.	Not assessed in project	N/C
	Sequential switching for circuit of serial contacts of redundant signals to avoid the common mode failure of the welding of both contacts, the switching on and off does not happen simultaneously, so that one contact always switches without current.	Sequential switching for non-concurrent design to avoid the common mode failure.	Р

# 8.3 List of well-tried safety principles

Table D.2 — Well-tried safety principles
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Clause	Requirement + Test	Result - Remark	Verdict
	Positive mechanically linked contacts Use of positively mechanically linked contacts for, e. g. monitoring function [see EN 292–2:1991 (ISO/TR 12100- 2:1992), 3.5].	MOSFET used, no such case	N/A
	<ul> <li>Fault avoidance in cables</li> <li>To avoid short circuit between two adjacent conductors:</li> <li>use cable with shield connected to the protective bonding circuit on each separate conductor, or</li> <li>in flat cables, use of one earthed conductor between each signal conductors.</li> </ul>	PCBA board, no such case	N/A
	Separation distance Use of sufficient distance between position terminals, components and wiring to avoid unintended connections.	Not this situation	N/A
	Energy limitation Use of a capacitor for supplying a finite amount of energy, e.g. in timer application.	No such case	N/A
	Limitation of electrical parameters Limitation in voltage, current, energy or frequency resulting, e. g. in torque limitation, hold-to-run with displacement/time limited, reduced speed, to avoid leading to an unsafe state.	All main components were de-rating used.	Р



Clause	Requirement + Test	Result - Remark	Verdict
	No undefined states Avoid undefined states in the control system. Design and construct the control system so that during normal operation and all expected operating conditions its state, e. g. its output(s) can be predicted.	All state is defined clearly, no undefined states.	Р
	Positive mode actuation Direct action is transmitted by the shape (and not by the strength) with no elastic elements, e. g. spring between actuator and the contacts, [see EN 1088:1995 (ISO 14119:1998), 5.1].	No such case	N/A
	Failure mode orientation Wherever possible, the device/circuit should fail to the safe state or condition.	The diagnostic measures are designed, in case of any faults detected, the system will go into safe state.	Ρ
	Oriented failure mode Oriented failure mode components or systems should be used wherever practicable [see EN 292–2:1991 (ISO/TR 12100- 2:1992), 3.7.4].	No such case	N/A
	Over-dimensioning De-rate components when used in safety circuits, e. g. by: Current passed through switched contacts should be less than half their rated current, The switching frequency of components should be less than half their rated value, and Total number of expected switching operation shall be ten times less than the device's electrical durability.	The charging and discharging MOSFETs are chosen with de-rating use.	Ρ
	Minimise possibility of faults Separate safety–related functions from the other functions.	Safety related circuit and non-safety related circuit are separated.	Р
	Balance complexity/simplicity Balance should be made between complexity to reach a better control and simplify to have a better reliability.	The balance between complexity controllability and simple reliability are taken into consideration during product design and development life cycle.	Ρ

--- END OF THE REPORT ---